

# Protecting Virtual Networks with DRONE

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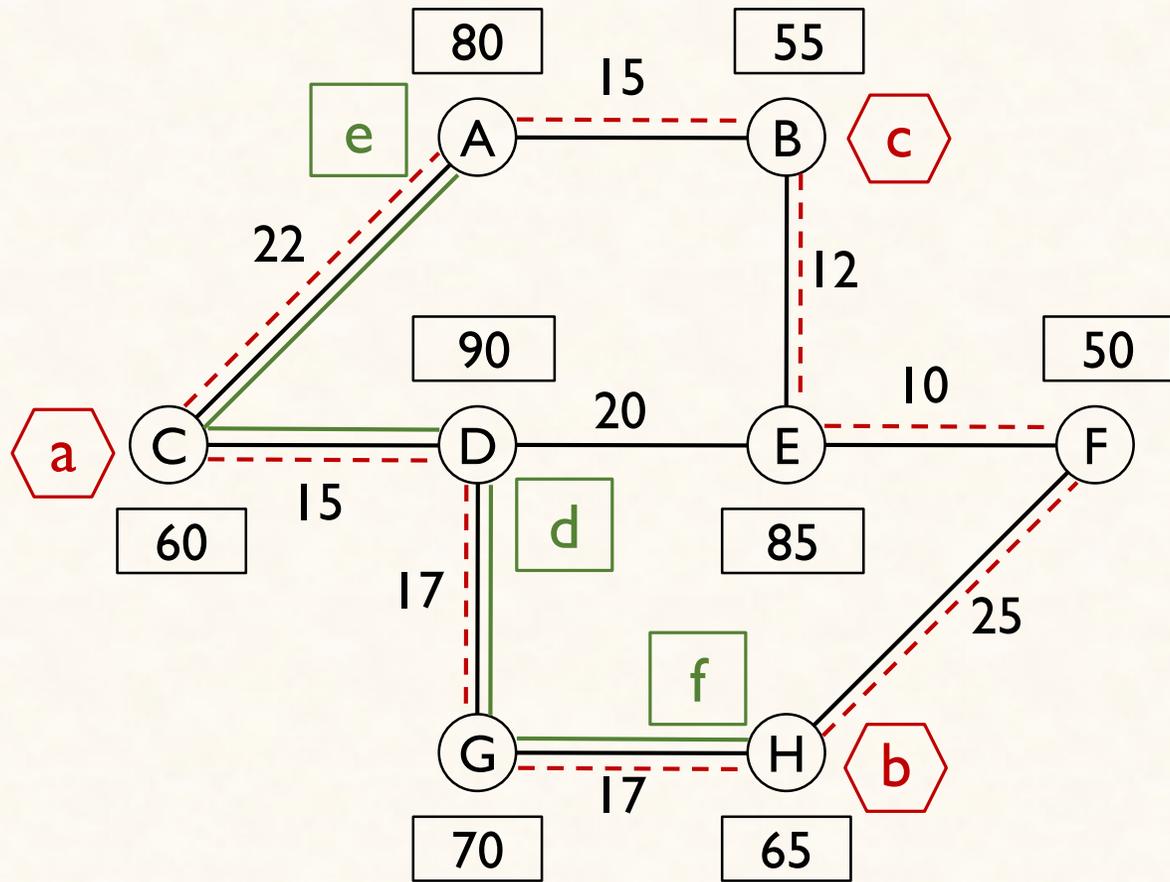
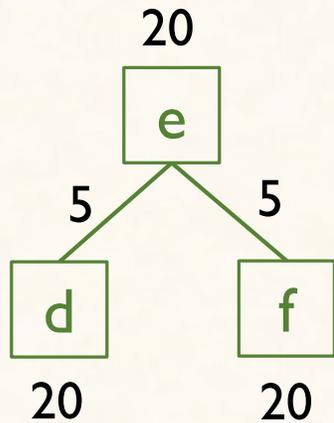
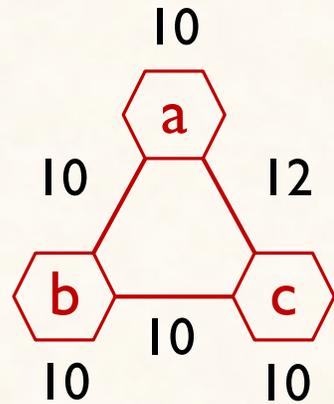
**UNIVERSITY OF WATERLOO**  
**FACULTY OF MATHEMATICS**  
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of Computer Science

Jeebak Mitra,  
Feng Zeng

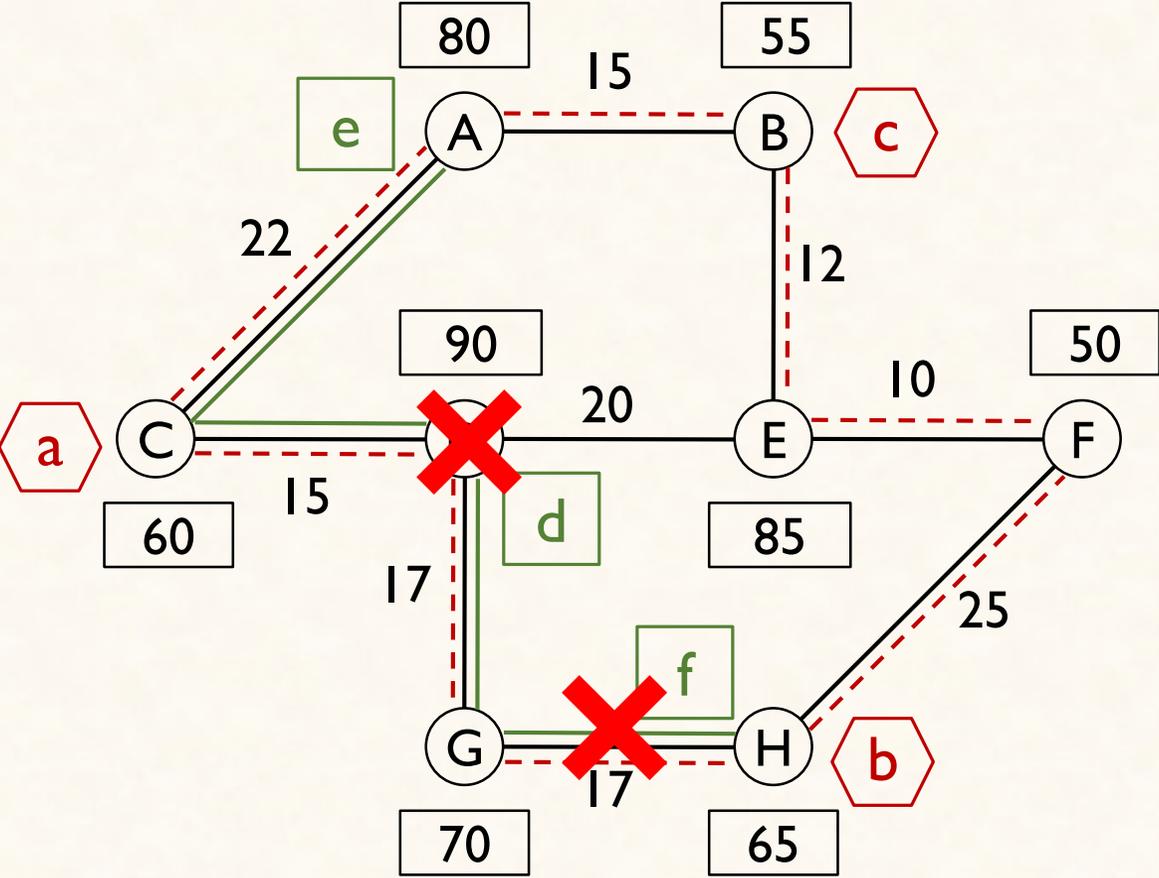
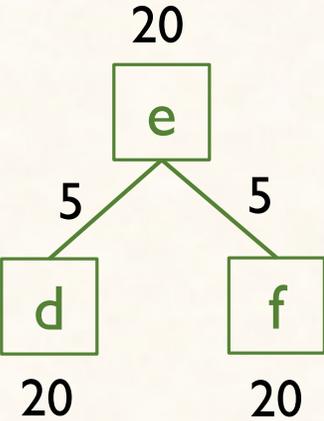
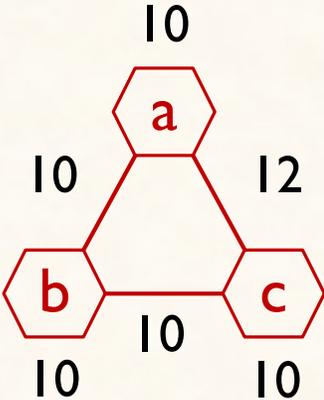


**HUAWEI**

# Virtual Network Embedding (VNE)



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# Transport Network Virtualization

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Transport Networks traditionally provided end-to-end connectivity

New use cases with virtualization: Full fledged VNs for customers

Tight SLA: Recover within 50ms of failure

## Key Question:

How to provide  $1 + 1$ -protection to an entire virtual network in a resource efficient way?

# The Problem

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I + I- Protected Virtual Network Embedding  
(I + I- ProViNE)

# The Problem

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## 1 + 1- Protected Virtual Network Embedding (1 + 1- ProViNE)

Dedicated protection  
for each virtual  
resource

Primary VN: 

Backup VN: 

# The Problem

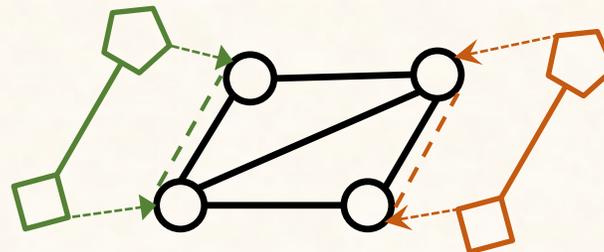
## I + I- Protected Virtual Network Embedding (I + I- ProViNE)

Dedicated protection  
for each virtual  
resource

Disjoint primary and  
backup embedding

Primary VN: 

Backup VN: 



# The Problem

## 1 + 1- Protected Virtual Network Embedding (1 + 1- ProViNE)

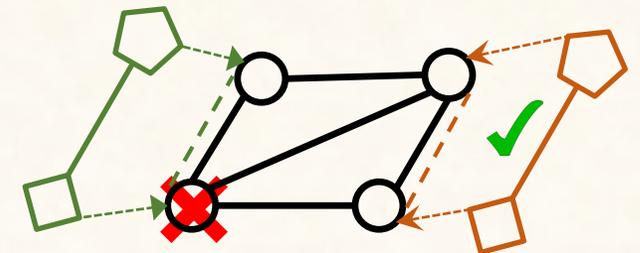
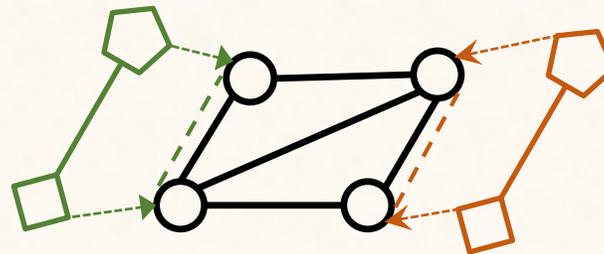
Dedicated protection  
for each virtual  
resource

Disjoint primary and  
backup embedding

Guaranteed Service  
under single physical  
node failure

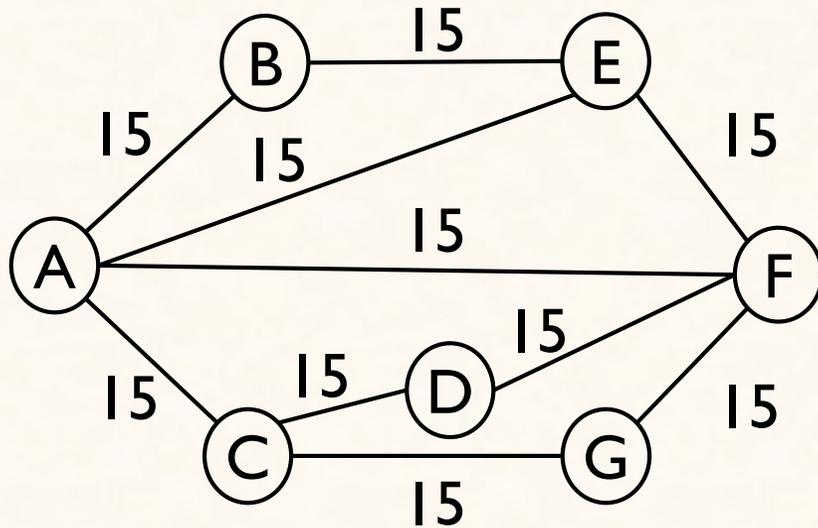
Primary VN: 

Backup VN: 

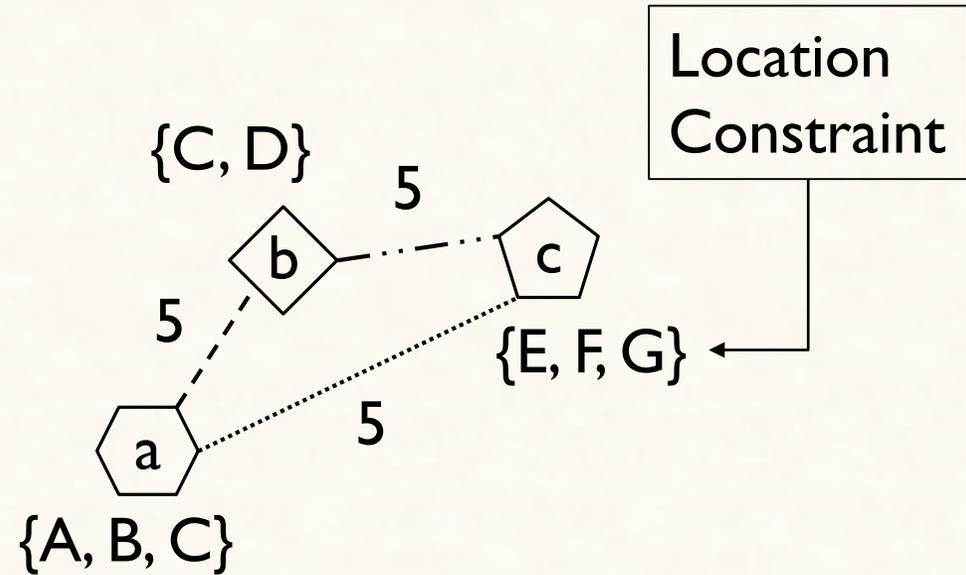


# I + I-ProViNE: Example

Given



Physical Network  
(G)

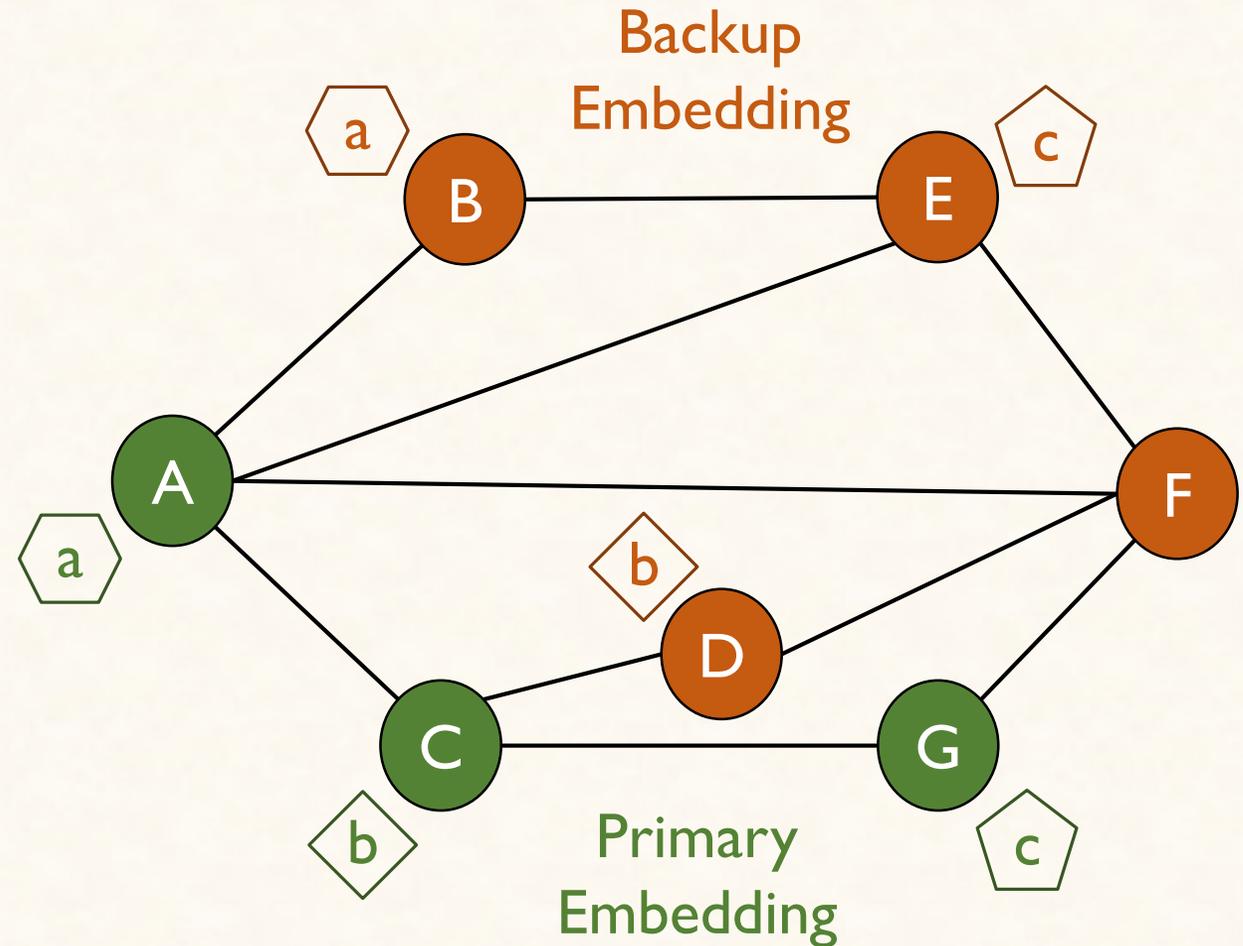


Virtual Network  
(G')

# I + I-ProViNE: Example

Find two disjoint embedding of  $G'$  on  $G$

Two disjoint embedding of each virtual node

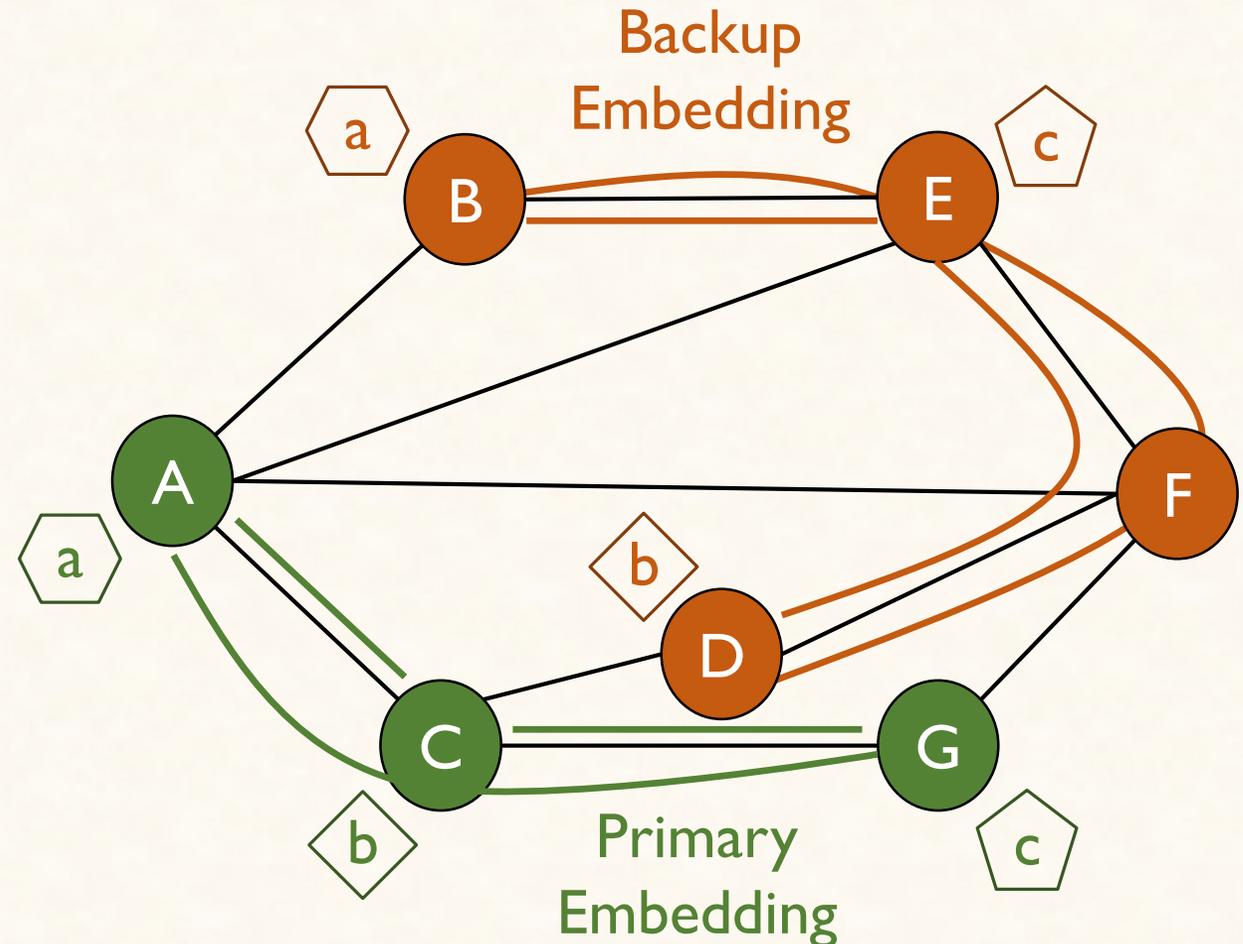


# I + I-ProViNE: Example

Find two disjoint embedding of  $G'$  on  $G$

Two disjoint embedding of each virtual node

Two disjoint embedding of each virtual link



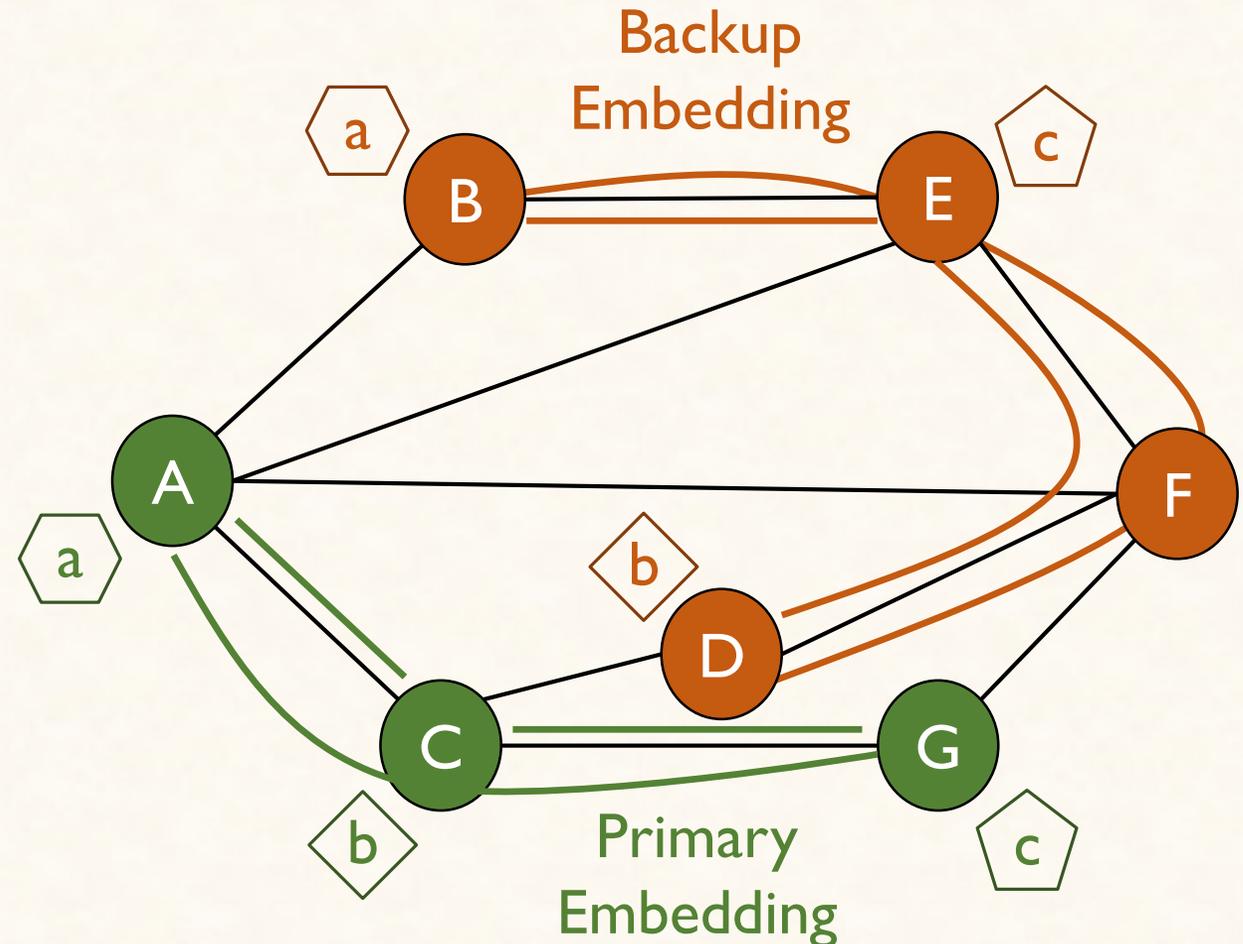
# I + I-ProViNE: Example

Find two disjoint embedding of  $G'$  on  $G$

Two disjoint embedding of each virtual node

Two disjoint embedding of each virtual link

Objective: Minimize total bandwidth cost



# Our Proposal

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## Dedicated Protection for Virtual Network Embedding (DRONE)

A suit of solutions to I + I-ProViNE

**OPT-DRONE**

ILP-based optimal solution

**FAST-DRONE**

Fast heuristic

# State-of-the-art

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## PAR\*

Quadratic Integer Program

Maximizes Acceptance Ratio

First fit for node and Suurballe's alg. for link embedding, respectively

## DRONE

Integer Linear Program

Minimizes Bandwidth Cost

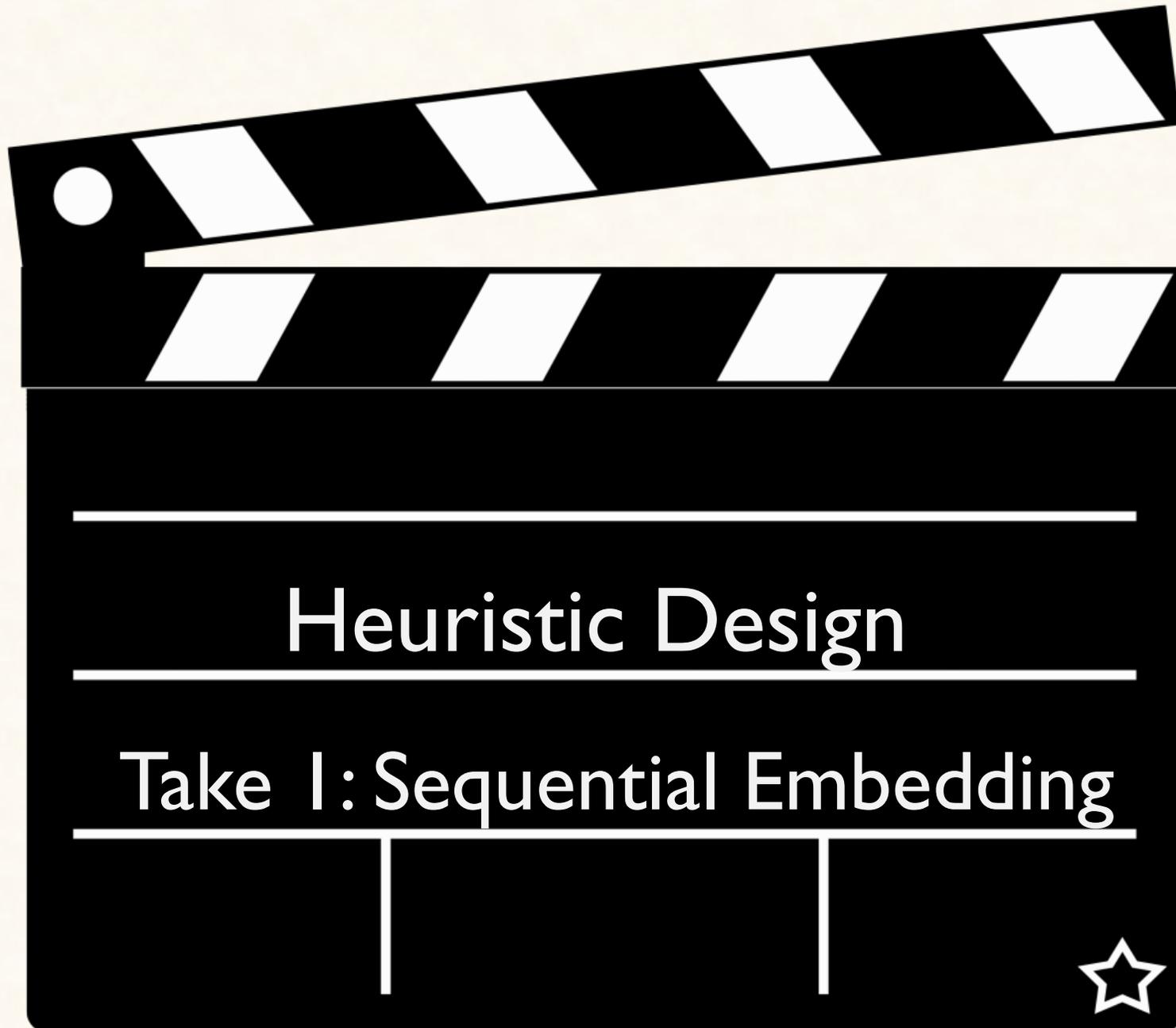
Graph partition based heuristic

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\*Ye, Zilong, et al. "Survivable Virtual Infrastructure Mapping With Dedicated Protection in Transport Software Defined Networks." *Journal of Optical Communications and Networking* 7(2): A183-A189, 2015.

## OPT-DRONE:

Integer Linear Program (ILP) model for optimal solution to I + I-ProViNE that **minimizes physical bandwidth allocation cost**

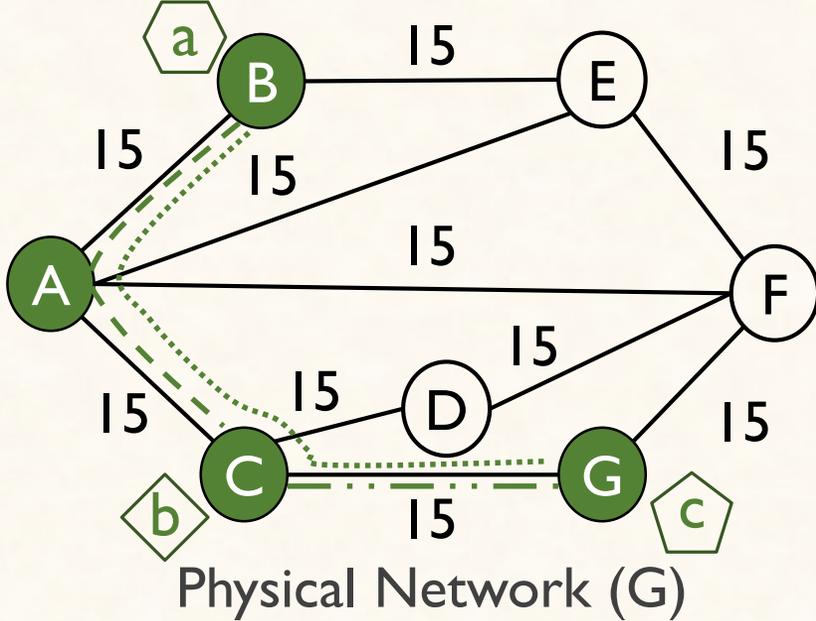
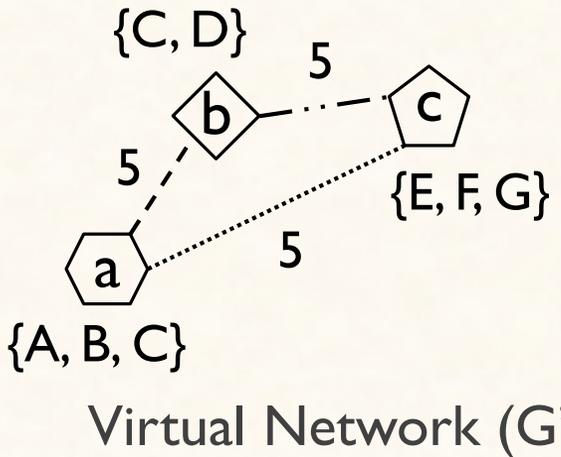


# Heuristic Design

Take 1: Sequential Embedding

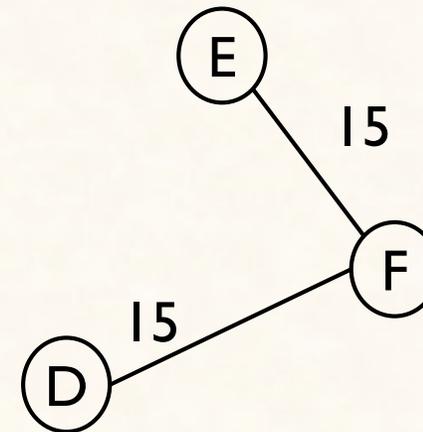
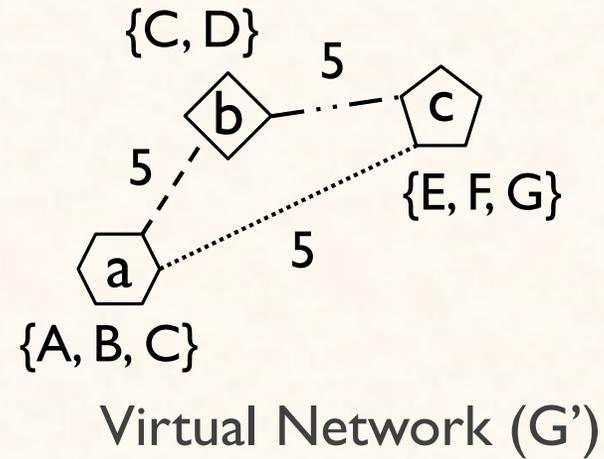


Embed the VN first  
(primary embedding)



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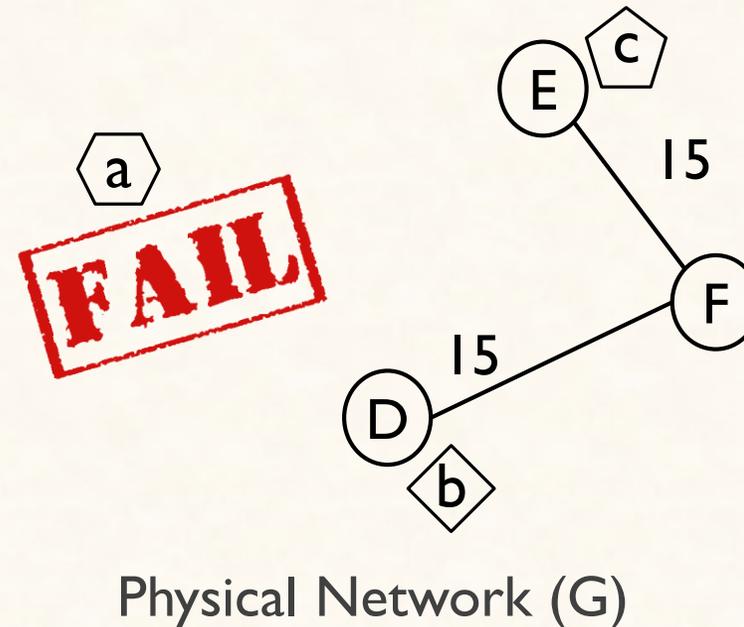
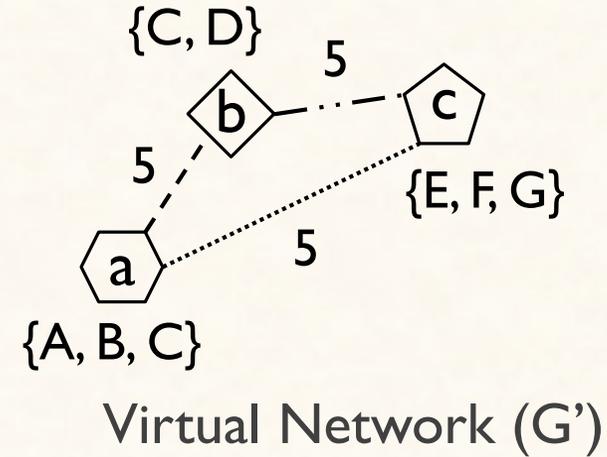
Remove physical resources  
in primary embedding



Embed the VN first  
(primary embedding)

Remove physical resources  
in primary embedding

Embed the VN again  
(backup embedding)



# Why Sequential Embedding can Fail?

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Physical Node and Link selection for **primary** can make **backup** embedding **infeasible**

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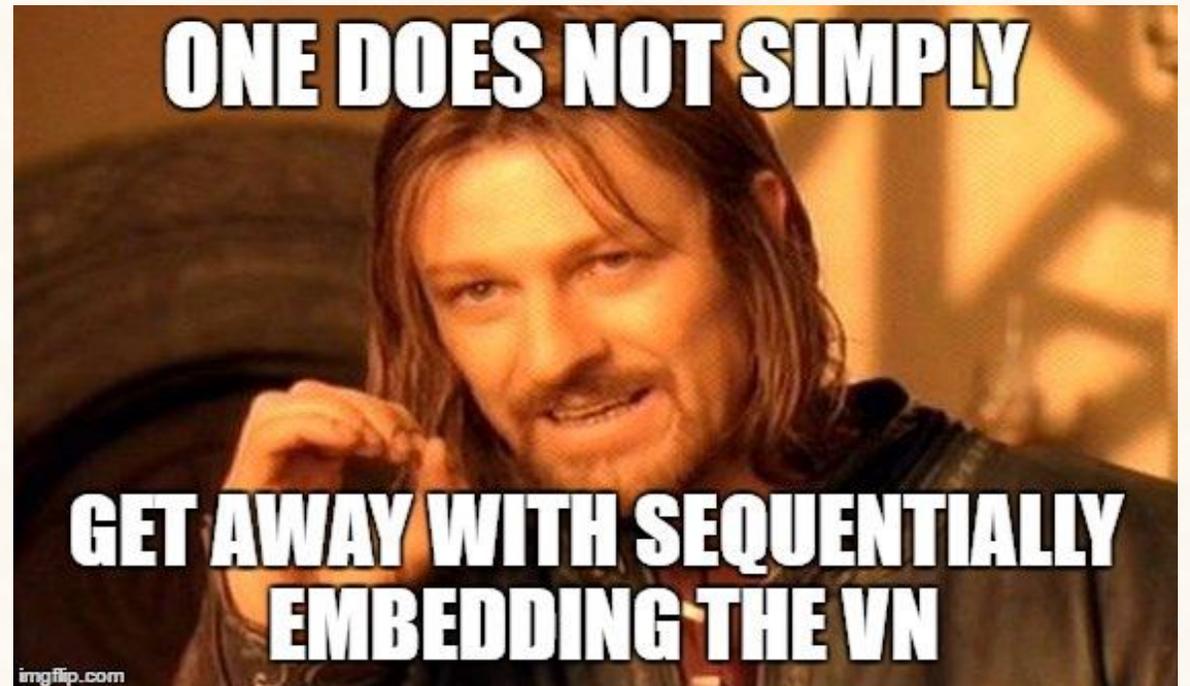
*Not Considered by Sequential Embedding!*

# Take Away

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Embed primary and backup  
at the same time, **not**  
**sequentially**

Consider **infeasibility** of  
backup embedding while  
doing the primary





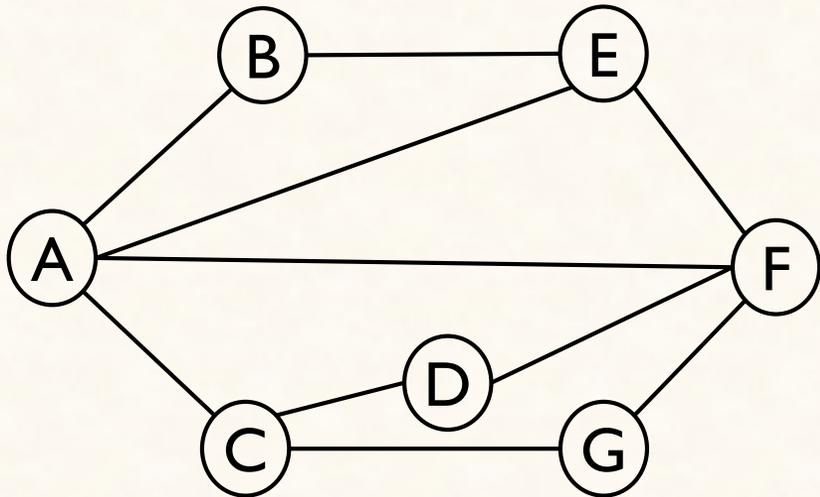
Heuristic Design

Take n: FAST-DRONE

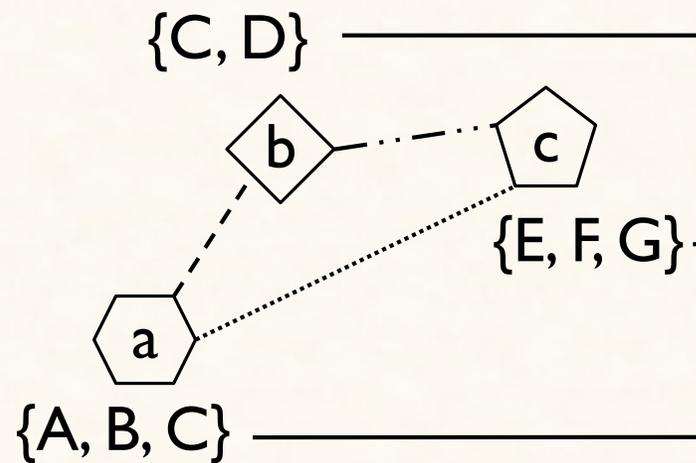


# FAST-DRONE: Solution Approach

Reformulate the problem as a special case of Graph Partitioning



Physical Network Graph  
 $G = (V, E)$

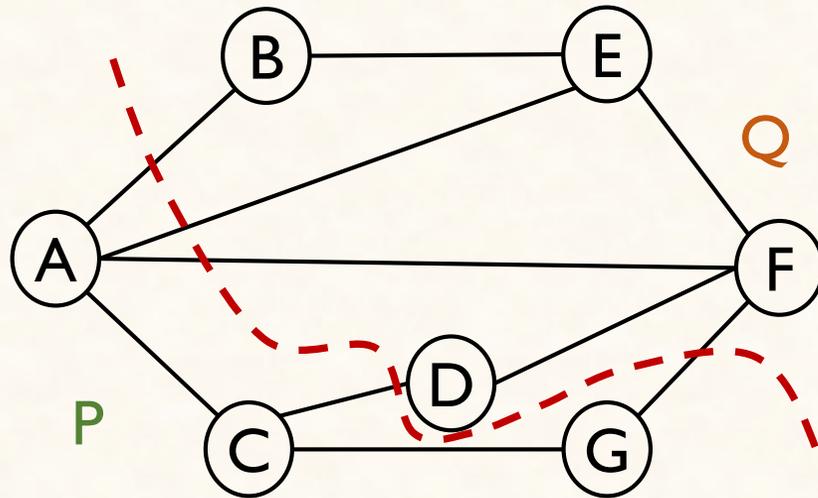


Virtual Network Graph  
 $G' = (V', E')$

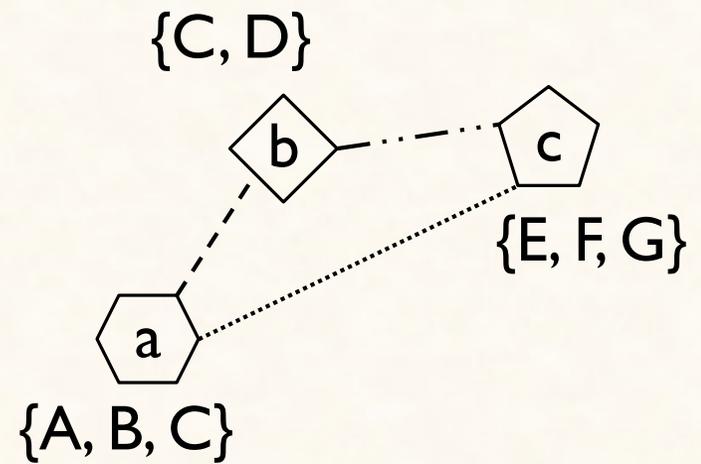
A Set of location constraints  
 $L = \{L_{u'} \mid L_{u'} \subseteq V, \forall u' \in V'\}$

# FAST-DRONE: Solution Approach

Partition  $G$  into two node-disjoint partitions  $P$  and  $Q$  for the primary and the backup embedding



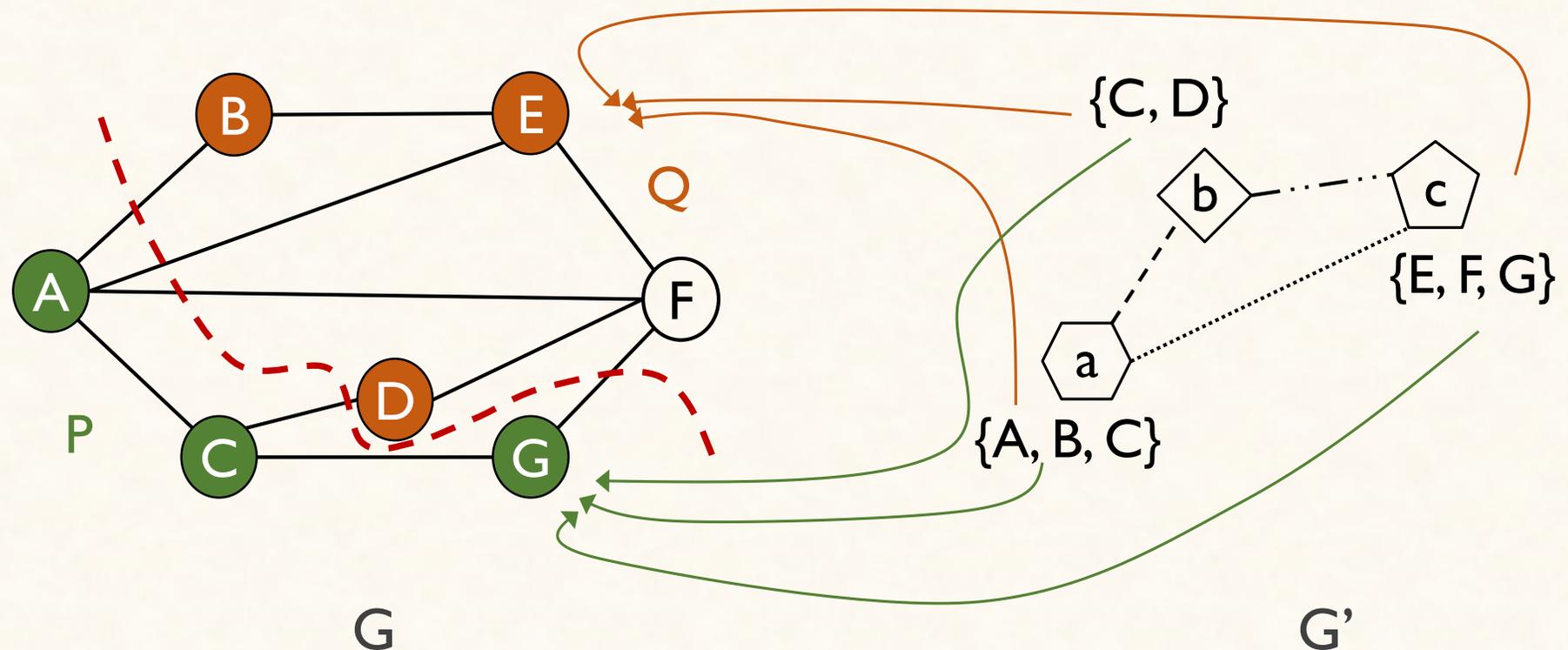
$G$



$G'$

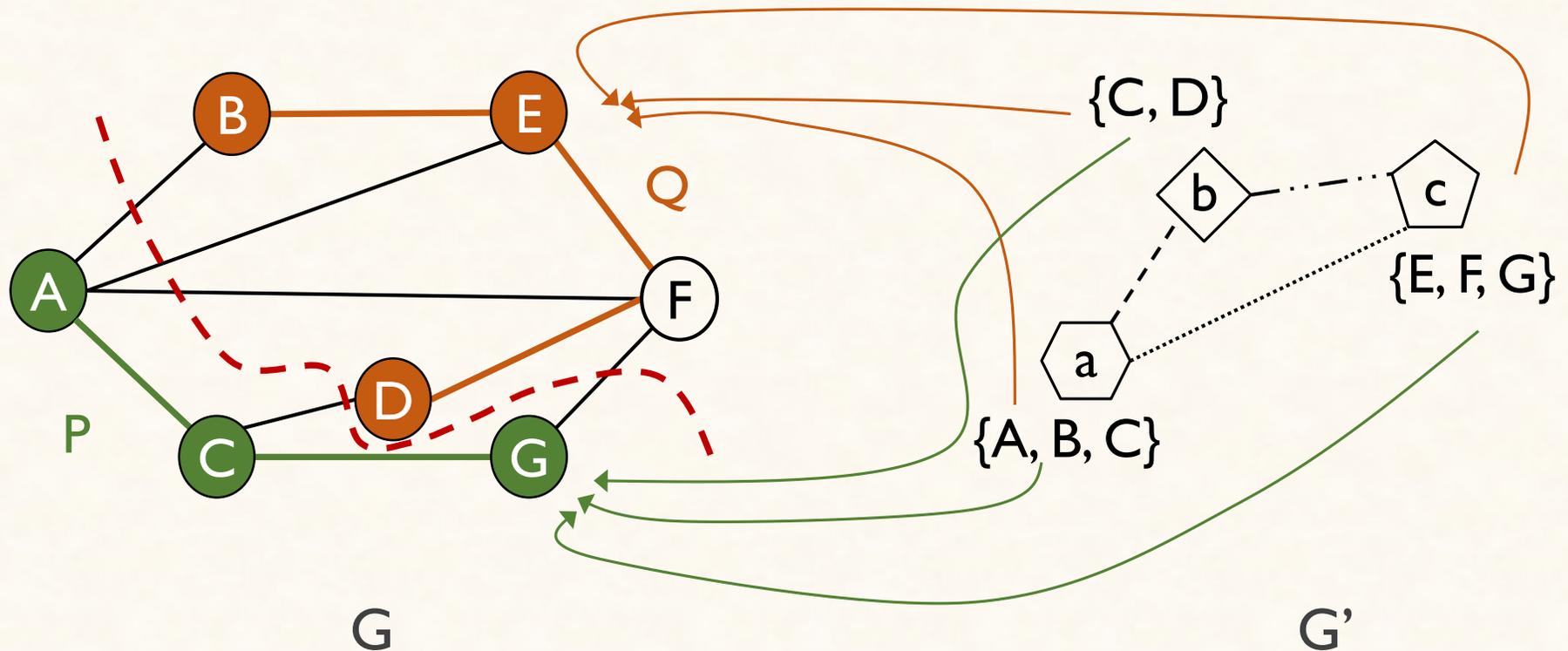
# FAST-DRONE: Solution Approach

$P$  and  $Q$  each satisfies at least one location constraint from each set  $L_u$ ,



# FAST-DRONE: Solution Approach

The nodes satisfying the location constraints of  $L_u$ , in **P** and **Q** are connected



# What does the restructuring say?

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I + I-ProViNE is **at least as hard** as jointly solving *Balanced Graph Partitioning* and *Unsplittable Multi-commodity flow with unknown sources and destinations*

# FAST-DRONE: 3-phase algorithm

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Intuition from restructuring: Partition the Physical Network in some way and embed the VN & backup in parallel

# FAST-DRONE: 3-phase algorithm

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Phase-I: Compute primary and backup embedding of virtual nodes

# FAST-DRONE: 3-phase algorithm

---

Intuition from restructuring: Partition the Physical Network in some way and embed the VN & backup in parallel

Phase-I: Compute primary and backup embedding of virtual nodes

Phase-II: Partition the physical network based on node embedding

# FAST-DRONE: 3-phase algorithm

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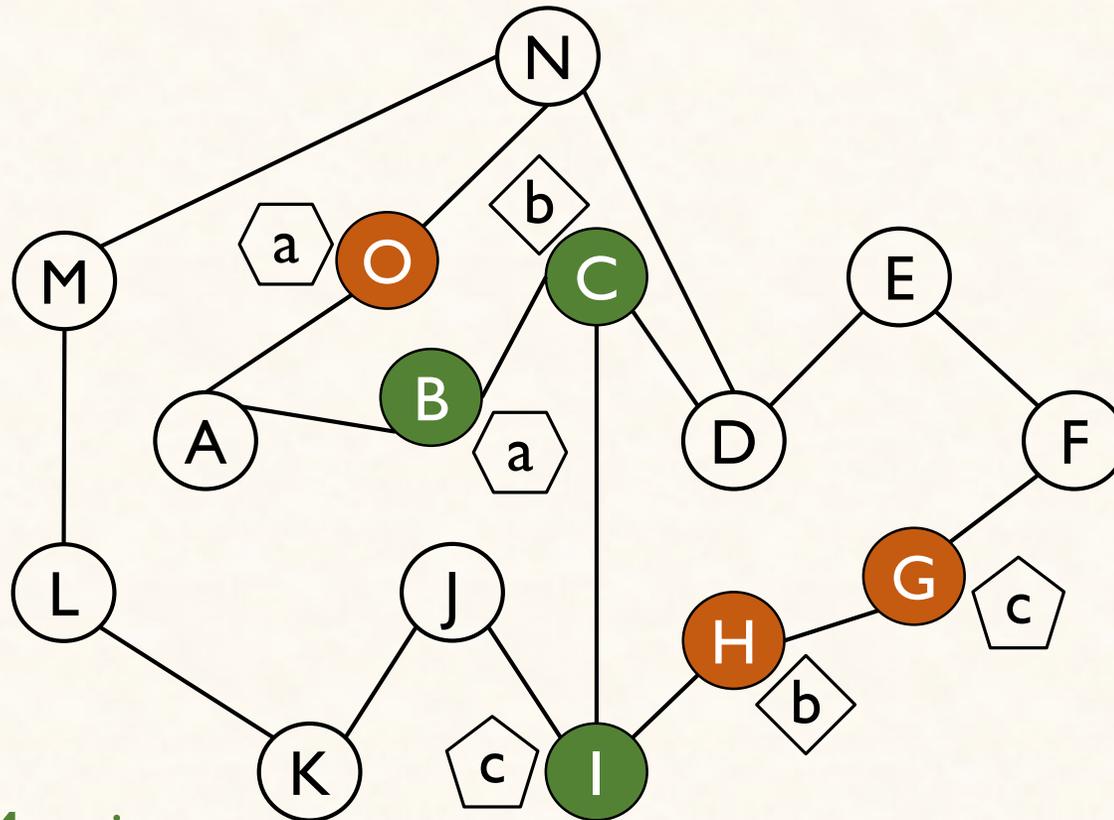
Intuition from restructuring: Partition the Physical Network in some way and embed the VN & backup in parallel

Phase-I: Compute primary and backup embedding of virtual nodes

Phase-II: Partition the physical network based on node embedding

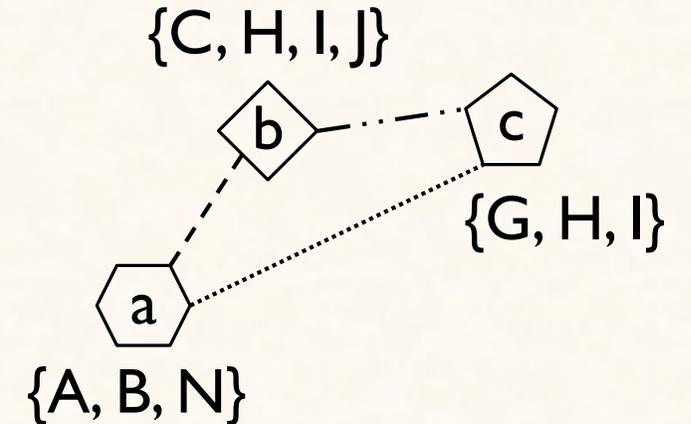
Phase-III: Embed virtual links inside primary and backup partitions

# Phase – I: Node Mapping Phase



Output:  
Primary Mapping  
Backup Mapping

Physical Network - G



Virtual Network - G'

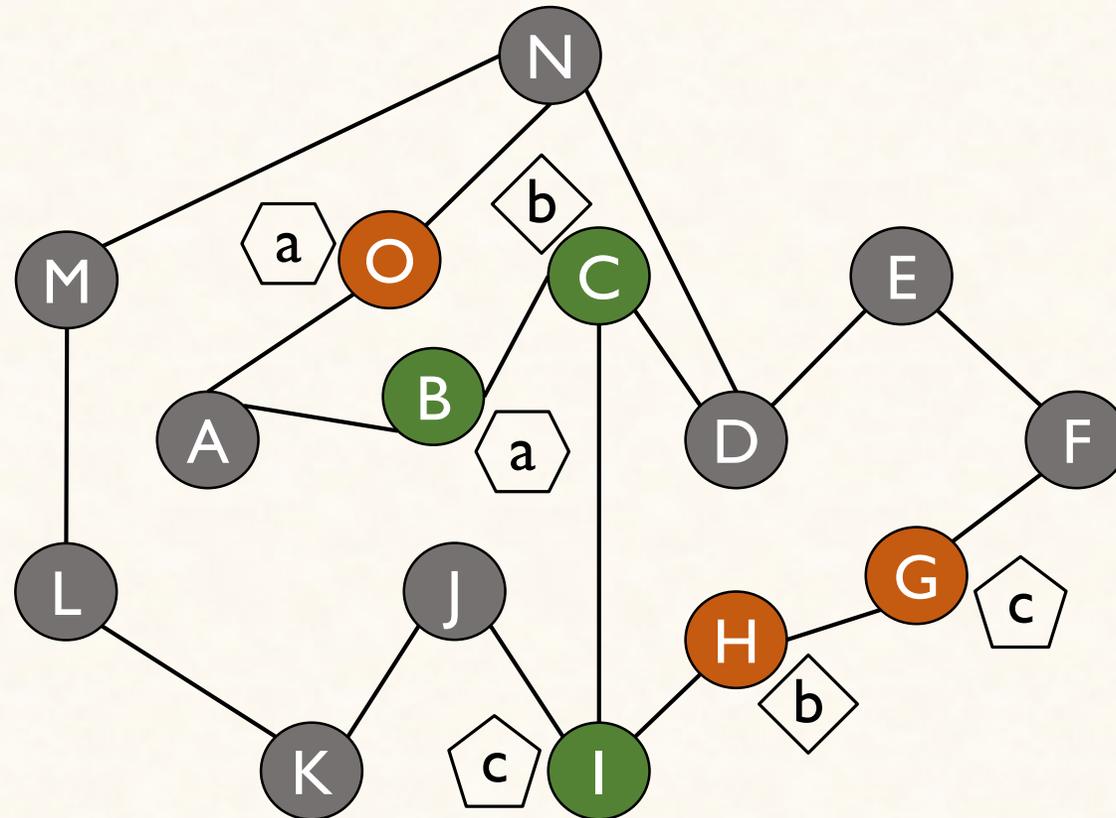
# Phase – II: Partitioning Phase

Input:

Seed Primary Partition

Seed Backup Partition

Un-partitioned Nodes



Physical Network - G

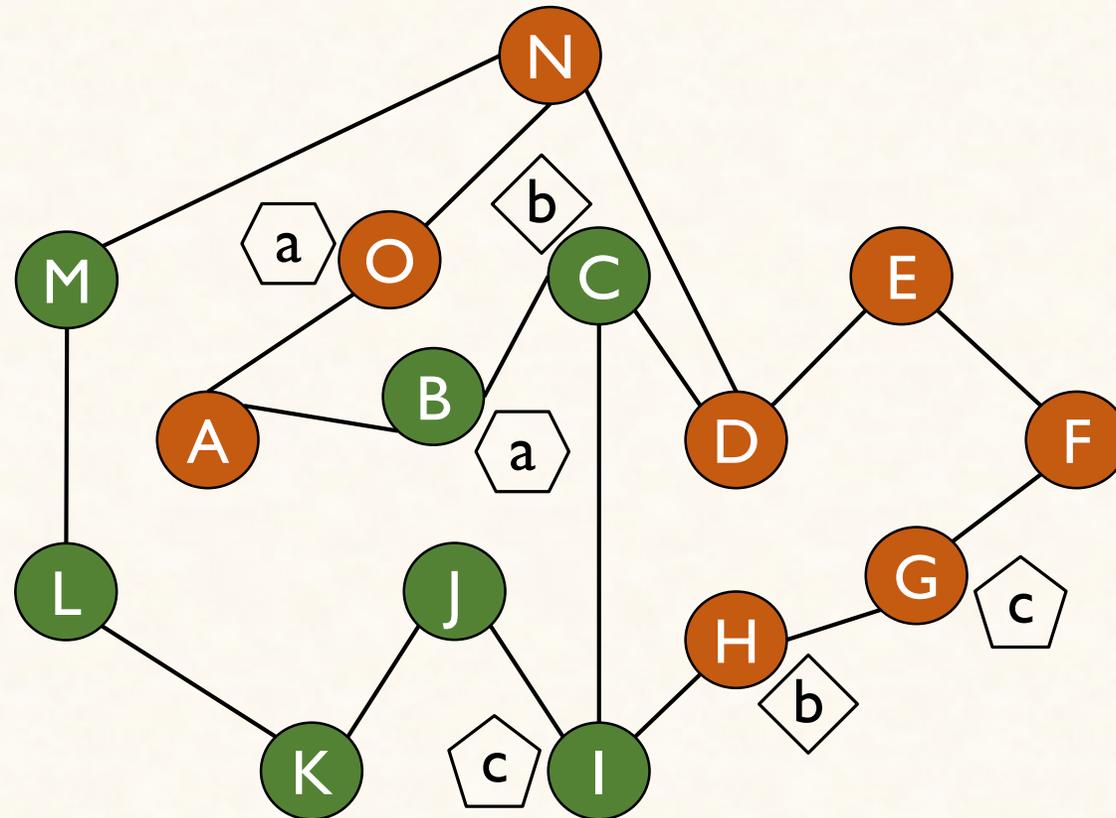
# Phase – II: Partitioning Phase

Grow each seed partition to include all physical nodes.

Output:

Primary Partition

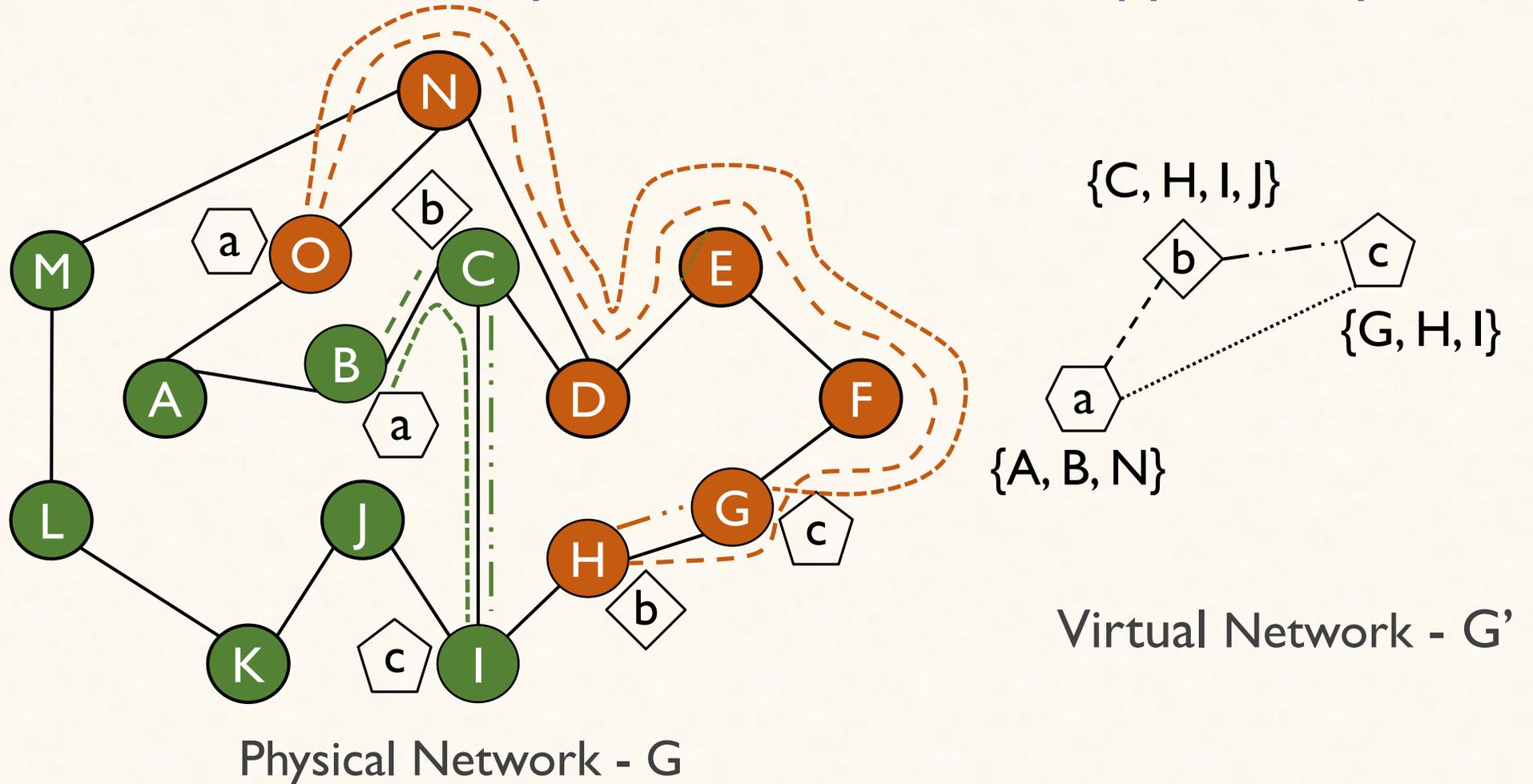
Backup Partition



Physical Network - G

# Phase – III: Link Mapping Phase

Map virtual links on shortest path between their mapped endpoints



# Evaluation: Setup

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- ❖ FAST-DRONE compared with OPT-DRONE and PAR\*
- ❖ Physical Network
  - ❖ 50 – 150 node synthetic topology
  - ❖ Mean degree between 2.4 – 4.4
- ❖ Virtual Network with  $\leq 16$  nodes

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\*Ye, Zilong, et al. "Survivable Virtual Infrastructure Mapping With Dedicated Protection in Transport Software Defined Networks." *Journal of Optical Communications and Networking* 7(2): A183-A189, 2015.

# FAST-DRONE Performance Highlights

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Within 15% of optimal on avg.

17.5% better than PAR on avg.



2-3 Orders of magnitude  
faster than Optimal

# Summary

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Two solutions to I+I-ProViNE: OPT-DRONE, FAST-DRONE

FAST-DRONE Outperforms stat-of-the-art

FAST-DRONE performs within ~15% of the Optimal

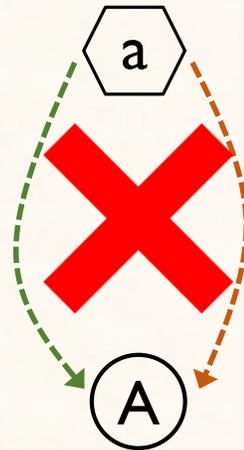


+ | Backup

# OPT-DRONE: Key Constraints

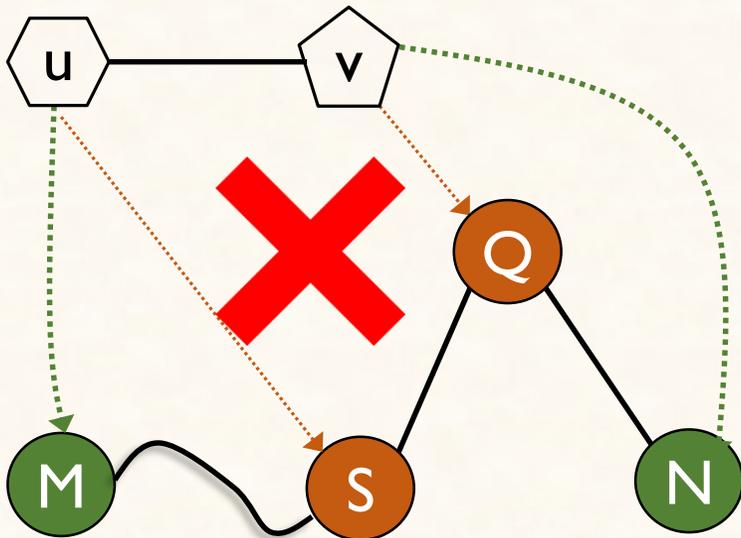
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A virtual node's **primary embedding** is **disjoint** from the set of physical nodes present in the virtual network's **backup embedding** and vice versa.

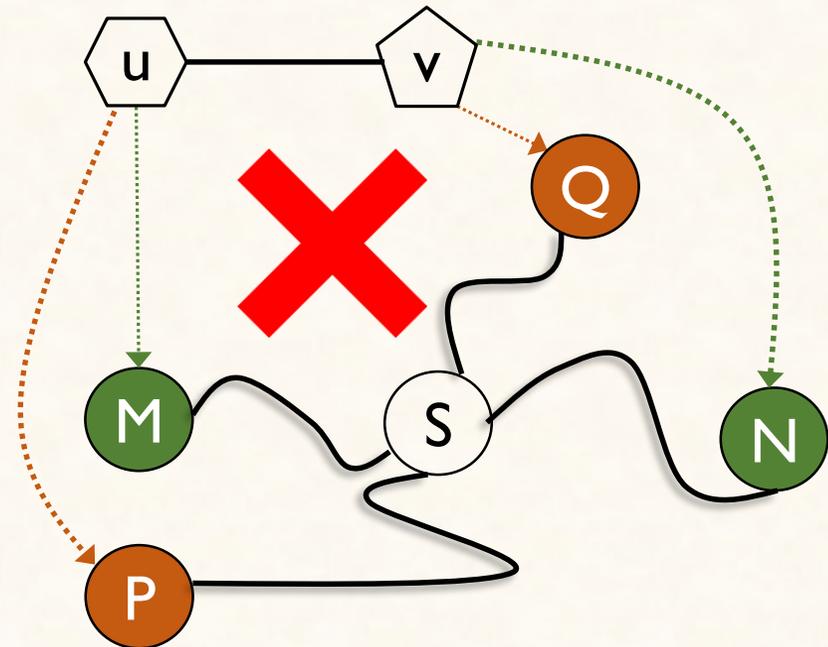


# OPT-DRONE: Key Constraints

A virtual link's primary embedding is **link** and **node disjoint** from the set of physical links present in the virtual network's backup embedding and vice versa.



No Link Sharing

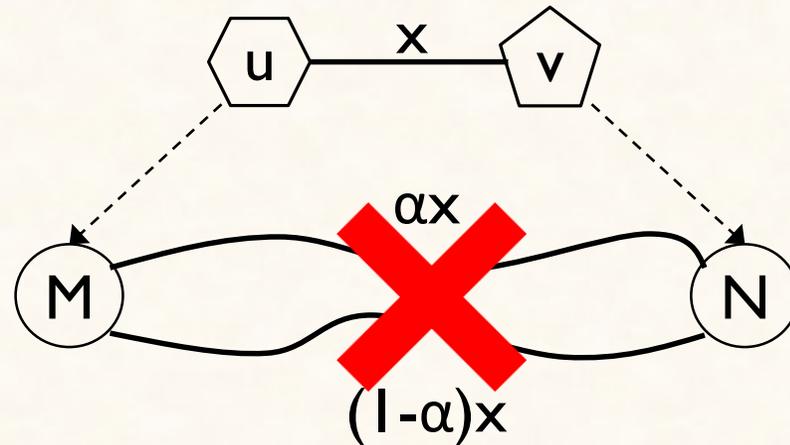


No Node Sharing

# OPT-DRONE: Key Constraints

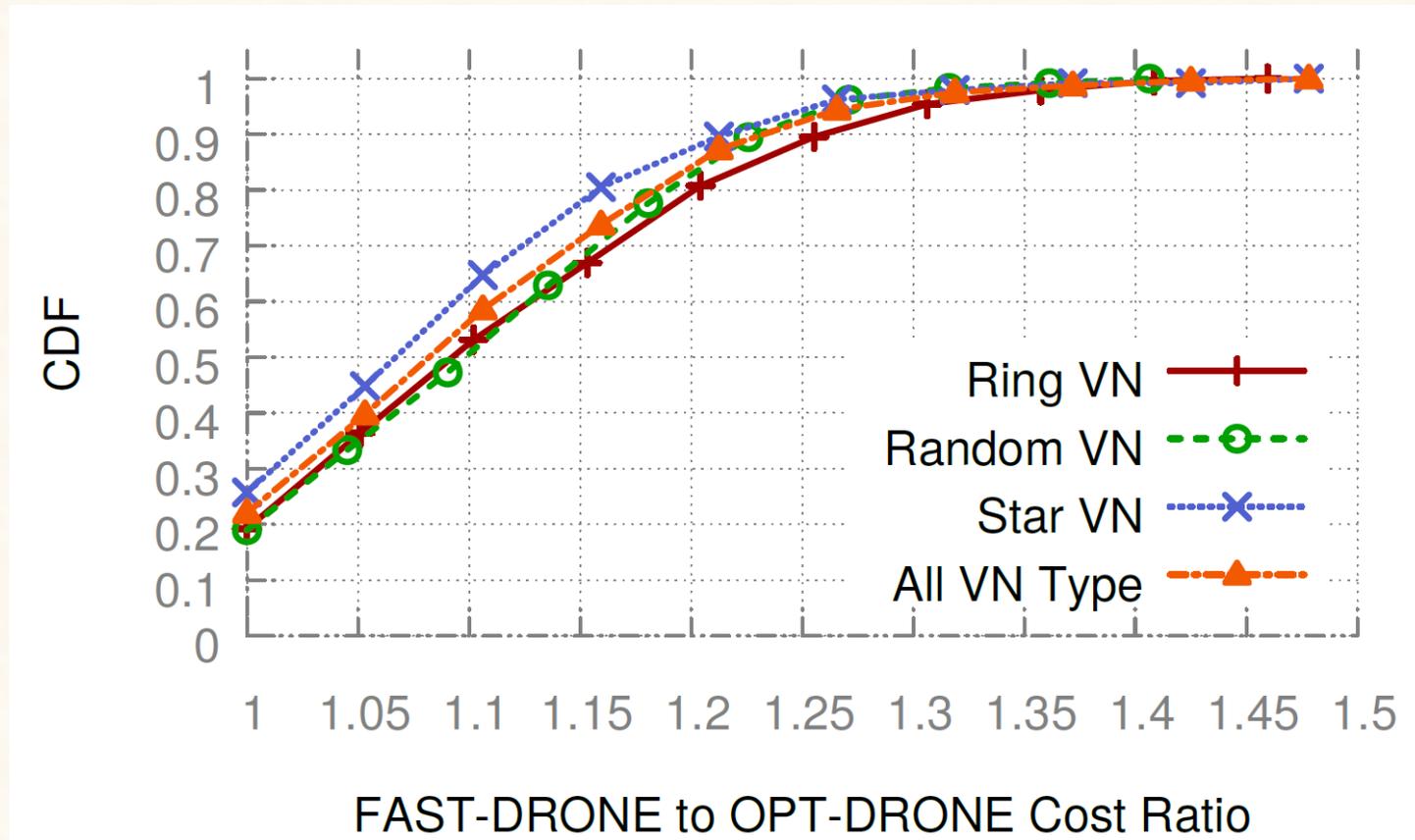
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A virtual link's demand cannot be satisfied using multiple physical paths.

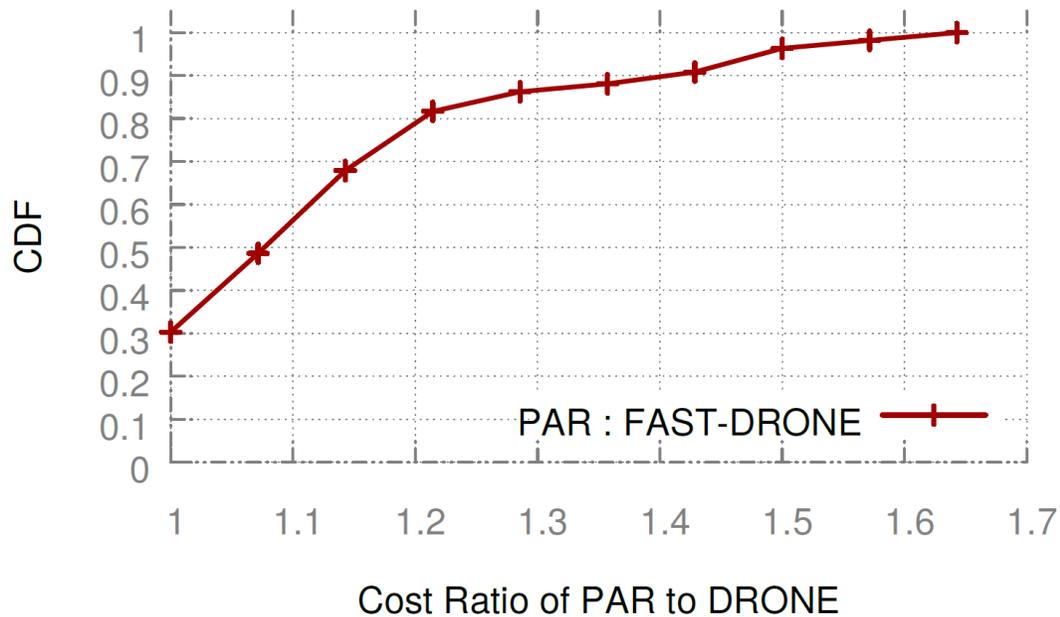


At least as hard as *Unsplittable Multi-Commodity Flow with Unknown Source & Destination* (NP-Hard)

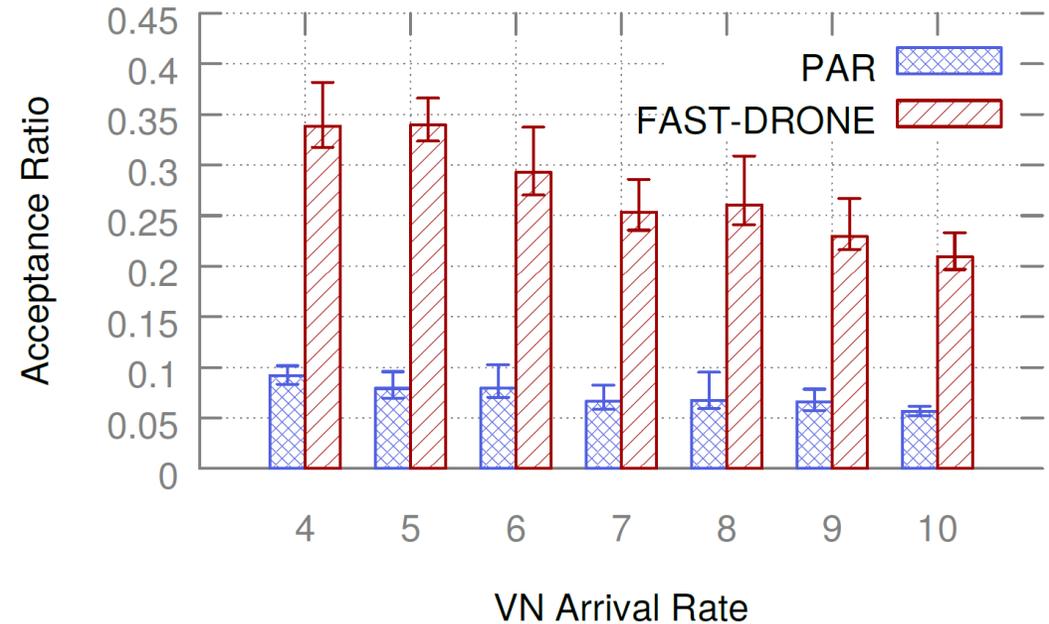
# FAST-DRONE vs OPT-DRONE



# FAST-DRONE vs PAR



Resource Efficiency



Acceptance Rate  
(From Journal Submission)