# University of Regina Department of Mathematics and Statistics 

MATH431/831 - Differential Geometry - Winter 2014

## Homework Assignment No. 2

1. Consider the helix, as defined on page 2, Ch. 2 (Curves in Space) of the notes.
(a) Calculate the torsion of the helix at an arbitrary point. Hint. Use the parametrization by arc length and the formula ${ }^{1} B^{\prime}=-\tau N$.
(b) Show that the normal line at an arbitrary point on the helix (that is, the straight line through that point which contains the vector $\left.{ }^{2} N(s)\right)$ intersects the $z$ axis, and the angle between the two lines is equal to $\frac{\pi}{2}$.
(c) Show that the angle between the tangent line at any point of the helix and the $z$ axis (or, if you prefer, between the vectors $T$ and $e_{3}$ ) is independent of the point. In the terminology of Section 2.3 of the notes, we say that the helix is a curve of constant slope with respect to the vector $e_{3}$.
2. Let $\alpha:(a, b) \rightarrow \mathbb{R}^{3}$ be a curve parametrized by arc length such that $\alpha^{\prime \prime}(s) \neq 0$, for all $s$ in $(a, b)$ (see the assumption mentioned on the first page of Ch. 2 of the notes).
(a) Show that if the trace of $\alpha$ is contained in a plane, then the vectors $T(s)$ and $N(s)$ are parallel to that plane. Hint. Consider a vector $v$ perpendicular to the plane and a point $P$ in the plane. For any point $\alpha(s)$ on the curve, the vector $\alpha(s)-P$ is parallel to the plane, so it's perpendicular to $v$. You only need to show that both $\alpha^{\prime}(s)$ and $\alpha^{\prime \prime}(s)$ are perpendicular to $v$ (keyword: dot product).
(b) Show that the trace of $\alpha$ is contained in a plane if and only if $\tau(s)=0$, for all $s$.
3. (a) If $\kappa>0$ and $\tau$ are two given numbers, determine all curves in space with constant curvature $\kappa$ and constant torsion $\tau$. Hint. It is sufficient to find one such curve (why?). Use question 1 above.
(b) Let $\alpha:(a, b) \rightarrow \mathbb{R}^{3}$ be a curve with constant curvature $\kappa>0$ and torsion equal to 0 at any point. Show that the trace $\alpha$ is a piece of a of a circle of radius $1 / \kappa$.
(c) Show that the trace of the curve

$$
\alpha(t)=\left(\frac{4}{5} \cos t, 1-\sin t,-\frac{3}{5} \cos t\right)
$$

is a circle. Find the radius of the circle.
4. Finish the proof of Theorem 2.1.4. That is, compute $\alpha^{\prime \prime \prime}(t)$, calculate $\alpha^{\prime} \times \alpha^{\prime \prime}$ and ( $\alpha^{\prime} \times$ $\left.\alpha^{\prime \prime}\right) \cdot \alpha^{\prime \prime \prime}$, and prove the two formulas.
5. (Not to be marked.) This is an example intended to show what kind of phenomena can happen if we neglect the assumption made in the notes, Ch. 2, first page. Consider the curve $\alpha: \mathbb{R} \rightarrow \mathbb{R}^{3}$ given by

$$
\alpha(t)=\left\{\begin{array}{l}
\left(t, 0, e^{-\frac{1}{t^{2}}}\right), \text { if } t>0 \\
(0,0,0), \text { if } t=0 \\
\left(t, e^{-\frac{1}{t^{2}}}, 0\right), \text { if } t<0
\end{array}\right.
$$

(a) Show that the curve $\alpha$ is differentiable (that is, all its components are of class $C^{\infty}$ ) and regular. Consequently, the vector $T(t)$ is defined for any $t$.
(b) Show that $\kappa(0)=0$, consequently $N(0)$ (as well as $B(0)$ and $\tau(0)$ ) is not defined.
(c) Show that it is not possible to extend $N$ and $B$ by continuity at $t=0$ (they both have a jump at 0 ).

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[^0]:    ${ }^{1}$ Let $e_{1}=(1,0,0), e_{2}=(0,1,0), e_{3}=(0,0,1)$ be the canonical basis of $\mathbb{R}^{3}$. The cross product of two vectors $v=\left(v_{1}, v_{2}, v_{3}\right)=v_{1} e_{1}+v_{2} e_{2}+v_{3} e_{3}$ and $w=\left(w_{1}, w_{2}, w_{3}\right)=w_{1} e_{1}+w_{2} e_{2}+w_{3} e_{3}$ is given by

    $$
    v \times w=\left|\begin{array}{ccc}
    e_{1} & e_{2} & e_{3} \\
    v_{1} & v_{2} & v_{3} \\
    w_{1} & w_{2} & w_{3}
    \end{array}\right|
    $$

    ${ }^{2}$ General Formula: the line through the point $P=\left(x_{0}, y_{0}, z_{0}\right)$ which contains the vector $v=\left(v_{1}, v_{2}, v_{3}\right)$ has equations $\frac{x-x_{0}}{v_{1}}=\frac{y-y_{0}}{v_{2}}=\frac{z-z_{0}}{v_{3}}$.

