## Math 535 - General Topology Additional notes

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## **1** Partitions of unity

**Definition 1.1.** Let X be a topological space and  $f: X \to \mathbb{R}$  a continuous function. The **support** of f is the closed subset

$$\operatorname{supp} f := \overline{\{x \in X \mid f(x) \neq 0\}} \subseteq X.$$

**Definition 1.2.** A cover  $\{U_{\alpha}\}_{\alpha \in A}$  of a space X is **locally finite** if for all  $x \in X$ , there is a neighborhood  $N_x$  of x that intersects only finitely many of the  $U_{\alpha}$ , i.e.

$$N_x \cap U_\alpha \neq \emptyset$$

for finitely many  $\alpha \in A$ .

Note that the definition applies to any kind of cover, not just open covers.

**Definition 1.3.** A partition of unity on a space X is a family of continuous functions  $\{\rho_{\beta} \colon X \to [0,1]\}_{\beta \in B}$  satisfying the following two properties.

- 1. The family  $\{\operatorname{supp} \rho_{\beta}\}_{\beta \in B}$  is locally finite.
- 2.  $\sum_{\beta \in B} \rho_{\beta}(x) = 1$  for all  $x \in X$ .

In particular, the supports  $\{\operatorname{supp} \rho_{\beta}\}_{\beta \in B}$  form a cover of X, and for all  $x \in X$ ,  $\rho_{\beta}(x) = 0$  for all except finitely many indices  $\beta \in B$ .

The partition of unity is **subordinate** to a cover  $\{U_{\alpha}\}_{\alpha \in A}$  of X if for all  $\beta \in B$ , there is an index  $\alpha = \alpha(\beta) \in A$  satisfying

$$\operatorname{supp} \rho_{\beta} \subseteq U_{\alpha(\beta)}.$$

Remark 1.4. One could assume WLOG that the indexing set B is A. Indeed, one could add together the functions  $\rho_{\beta}$  supported on the same  $U_{\alpha}$ , and consider the constant zero function for each index  $\alpha$  that does not appear as  $\alpha(\beta)$ .

It is useful to have partitions of unity subordinate to any open cover. We will find conditions on a space that make this always possible.

## 2 Paracompactness

**Definition 2.1.** Let  $\mathcal{U}$  be a cover of X. A **refinement** of  $\mathcal{U}$  is a cover  $\mathcal{V}$  of X such that every member  $V \in \mathcal{V}$  is a subset of some  $U \in \mathcal{U}$ .

In other words, a cover  $\{V_{\beta}\}_{\beta \in B}$  is a refinement of the cover  $\{U_{\alpha}\}_{\alpha \in A}$  if for all  $\beta \in B$ , there is an index  $\alpha(\beta) \in A$  satisfying

$$V_{\beta} \subseteq U_{\alpha(\beta)}.$$

Example 2.2.  $\{(n, n+2)\}_{n\in\mathbb{Z}}$  is a refinement of the cover  $\{\mathbb{R}\}$  of  $\mathbb{R}$ .

*Example 2.3.*  $\{(0,\infty)\}$  is a refinement of the cover  $\{(n,\infty)\}_{n=0}^{\infty}$  of  $(0,\infty)$ .

**Definition 2.4.** A topological space X is **paracompact** if every open cover of X admits a locally finite open refinement.

*Remark* 2.5. Some authors (e.g. Bredon, Willard) include the Hausdorff condition in the definition of paracompact. Other authors (e.g. Munkres, Wikipedia) do not assume that the space is Hausdorff. We will *not* assume that the definition of paracompact includes Hausdorff.

Example 2.6. Every compact space is paracompact.

*Example 2.7.*  $\mathbb{R}^n$  is paracompact. This will follow from 2.13.

**Definition 2.8.** A space is  $\sigma$ -compact if it is a countable union of compact subspaces.

Example 2.9.  $\mathbb{R}^n$  is  $\sigma$ -compact, as it is the union of closed balls  $\mathbb{R}^n = \bigcup_{k \in \mathbb{N}} \overline{B_k(0)}$ .

*Example 2.10.* Any closed subset of  $\mathbb{R}^n$  is  $\sigma$ -compact.

*Example* 2.11. More generally, any closed subset  $C \subseteq X$  of a  $\sigma$ -compact Hausdorff space X is  $\sigma$ -compact.

*Example 2.12.* Any second-countable manifold is  $\sigma$ -compact. More generally, any second-countable locally compact space is  $\sigma$ -compact (c.f. Homework 12 #2).

**Proposition 2.13.** Every locally compact,  $\sigma$ -compact, Hausdorff space is paracompact.

**Proposition 2.14.** A closed subspace of a paracompact space is paracompact.

*Proof.* Homework 12 #3.

**Lemma 2.15.** If  $\{A_i\}_{i \in I}$  is a locally finite collection of subsets  $A_i \subseteq X$ , then we have

$$\overline{\bigcup_{i\in I}A_i} = \bigcup_{i\in I}\overline{A_i}.$$

Proposition 2.16. Every paracompact Hausdorff space is normal.

**Proposition 2.17** (Shrinking lemma). Let X be a paracompact Hausdorff space and  $\{U_{\alpha}\}_{\alpha \in A}$ an open cover. Then there is a locally finite open cover  $\{V_{\alpha}\}_{\alpha \in A}$  satisfying  $\overline{V_{\alpha}} \subseteq U_{\alpha}$  for all  $\alpha \in A$ .

Note that the indexing set A is the same for both open covers. Note also that  $V_{\alpha}$  is allowed to be empty.

**Theorem 2.18** (Existence of partitions of unity). Let X be a paracompact Hausdorff space and  $\mathcal{U} = \{U_{\alpha}\}_{\alpha \in A}$  an open cover. Then there is a partition of unity on X subordinate to  $\mathcal{U}$ .

## 3 Applications to manifolds

**Theorem 3.1.** Any compact Hausdorff manifold can be embedded in  $\mathbb{R}^N$  for some N.

Proof. Let M be an m-dimensional compact Hausdorff manifold. For each  $x \in M$ , a coordinate chart about x consists of a homeomorphism  $\varphi_x \colon U_x \to V_x \subseteq \mathbb{R}^m$  where  $U_x$  is an open neighborhood of x and  $V_x$  is an open subset of  $\mathbb{R}^m$ . Since M is compact, the open cover  $\{U_x\}_{x \in M}$  admits a finite subcover  $\{U_1, \ldots, U_k\}$ . Since M is paracompact and Hausdorff, there exists a partition of unity  $\{\rho_i\}_{i=1}^k$  with  $\operatorname{supp} \rho_i \subseteq U_i$ .

For  $i = 1, \ldots, k$ , define maps  $h_i \colon M \to \mathbb{R}^m$  by

$$h_i(x) = \begin{cases} \rho_i(x)\varphi_i(x) & \text{if } x \in U_i \\ 0 & \text{otherwise} \end{cases}$$

These maps  $h_i$  are well defined and continuous. Now define the continuous map

$$g: M \to \underbrace{\mathbb{R} \times \ldots \times \mathbb{R}}^{k} \times \underbrace{\mathbb{R}^{m} \times \ldots \times \mathbb{R}^{m}}_{x \mapsto (\rho_{1}(x), \ldots, \rho_{k}(x), h_{1}(x), \ldots, h_{k}(x))}^{k} \cong \mathbb{R}^{k(m+1)}$$

Since M is compact and  $\mathbb{R}^N$  is Hausdorff, g is a closed map. To show that g is an embedding, it remains to show that g is injective.

Assume g(x) = g(y) for some  $x, y \in M$ . Then  $\rho_i(x) = \rho_i(y)$  for all *i*. Let *j* be an index where  $\rho_i(x) > 0$  and thus  $\rho_i(y) = \rho_i(x) > 0$ . We obtain

$$h_j(x) = h_j(y)$$
  

$$\rho_j(x)\varphi_j(x) = \rho_j(y)\varphi_j(y)$$
  

$$\Rightarrow \varphi_j(x) = \varphi_j(y)$$
  

$$\Rightarrow x = y$$

since  $\varphi_i$  is injective.

This example illustrates how partitions of unity on a manifold can be useful. Since many interesting manifolds are not compact, it would be useful to know when a (Hausdorff) manifold is paracompact.

**Theorem 3.2.** Let M be a Hausdorff manifold. Then M is paracompact if and only if each connected component of M is second-countable.

*Proof.* Let  $\{M_i\}_{i \in I}$  be the connected components of M. Recall that manifolds are locally pathconnected. Therefore  $M = \coprod_{i \in I} M_i$  is the coproduct of its connected components (which are the same as its path components).

( $\Leftarrow$ ) Note that any manifold is locally compact. Since  $M_i$  is locally compact and second-countable, it is  $\sigma$ -compact (by 2.12).

Since  $M_i$  is locally compact,  $\sigma$ -compact, and Hausdorff, it is paracompact (by 2.13). Since  $M = \coprod_{i \in I} M_i$  is a coproduct of paracompact spaces, it is paracompact (c.f. Homework 12 #4).

 $(\Rightarrow)$  Since  $M_i$  is connected, locally compact, paracompact, and Hausdorff, it is  $\sigma$ -compact (by 3.3).

Since  $M_i$  is  $\sigma$ -compact and every point  $x \in M_i$  has a second-countable neighborhood,  $M_i$  is second-countable (by 3.4).

**Proposition 3.3.** Let X be a connected, locally compact, paracompact, Hausdorff space. Then X is  $\sigma$ -compact.

**Proposition 3.4.** Let X be a  $\sigma$ -compact space such that every point  $x \in X$  has a second-countable neighborhood. Then X is second-countable.

Here is another application of partitions of unity.

**Proposition 3.5.** Every paracompact smooth manifold admits a Riemannian metric.

Yet another application is in defining integration on manifolds. One can define integration within a coordinate chart, and then on the entire manifold using a partition of unity.